

Figure 2 : Temperature and relative humidity versus time for one day in August in New Delhi (India).

Figure 1 shows the plant. During the charge mode (generally by night during the off-peak hours) the refrigerating machine is under operation and the glycol water is flowing through the tank with ABCD direction in order to crystallise the PCM contained in the nodules. During the discharge mode, the water glycol flowing with BHEFCB direction brings about the melting of the PCM. The stored cooling is thus recovered by the glycol water, which, by supplying the exchanger, makes it possible to cool the turbine inlet air. The melting point

of the PCM used here is 0°C.

It should be noted that during operation, the direction of the water glycol flow in the tank varies depending on whether it is the charge mode or it is the discharge mode. The tank is vertical and the fluid flows from the bottom to the top for the charge process and from the top to the bottom for the discharge process.

Thus, the refrigerating machine is running only to charge the tank during the off-peak hours of the electric requirement. To cool the turbine inlet air, only cold from storage is required.

2.3. Plant operation.

The installation is led so that the turbine provides constantly the required electric output by cooling the ambient air before its input in the turbine when it needs to be. According to the power that must be supplied by the turbine, inlet air temperature can be controlled by actuating the mixing three-ways valve (Figure 1). Thus the storage tank is partly by-passed to control the glycol water temperature at the inlet of the exchanger (in any case the temperature is limited to 0°C in order to avoid frost formation over the fins of the exchanger). The fluid flow rate in the exchanger remains constant while the one through the tank varies according to the electric requirement and the outside temperature.

3. SUMMARY OF PREVIOUS WORK ABOUT REFRIGERATION STORAGE

3.1. Presentation

The advantages of the storage process used here are numerous and obvious [3]. The disadvantages result

from the supercooling phenomenon. It is well state that PCM does not crystallise at the melting point (solid-liquid equilibrium) but at a lower temperature. This phenomenon increases the cost of operation or investment. The first work has analysed the supercooling of the material [2,3] while trying to reduce it by the addition of nucleating catalysts and by quantifying its influence on the process operation. The experimental installation, including a cylindrical tank of reduced size (1 m³ containing 2500 nodules)[3], made possible the thorough knowledge of the operation of this type of storage process. The influence of various parameters [3,4] is shown. A numerical simulation of the process has been developed and proved from the measurements made on the experimental set-up

3.2. Modelling

The numerical simulations, presented in several previous papers [4,5], consider the aspects of both the surrounding heat transfer fluid and the phase change material packed inside the nodules in the charge mode as well as in the discharge mode. The chilled fluid is flowing vertically respecting the natural stratification due to the density of the coolant.

3.2.1. Modelling the charge mode

The tank is divided into several meshes containing N nodules. Applying the laws of conservation of mass and energy to each layer yields :

$$\rho c_{Pf} V \frac{dT_c}{dt} = \rho c_{Pf} q_c (T_m - T_{m+1}) + \sum_{i=1}^N \Phi_i \quad (1)$$

where $T_c = (T_m + T_{m+1})/2$ is the average temperature of the heat transfer fluid of the layer (T_m and T_{m+1} are respectively the inlet and the outlet temperature of the layer) and Φ_i is the flux exchanged by the nodule i.

Even when the heat transfer fluid temperature is considered uniform in each layer, all the nodules of each layer do not simultaneously pass through the phase change at the melting temperature T_M because of the supercooling and the erratic character of the crystallisation. The nodules can be in different states (non-crystallised, entirely crystallised or partly crystallised) according to their own value of the beginning of the crystallisation.

Applying the nucleation laws [5], the number of new crystallisations and the corresponding fluxes can be calculated at each time t.

The quasistationary approximation [6] is applied to the determination of Φ_i during crystallisation.

Consider a nodule of inner radius r_i . Uniform cooling of its surface will result in a spherically symmetric crystallisation-front, $r = r_s(t)$ the inner radius of solid PCM, propagating inwards from $r = r_i$ with liquid at T_M for $0 \leq r \leq r_s(t)$ and solid for $r_s(t) \leq r \leq r_i$. Assuming constant thermal properties in each phase, the steady-state solution of the heat conduction in the solid has the form (θ is the temperature of the solid PCM):

$$\theta(r, t) = T_M + [T_c(t) - T_M] \frac{1 - \frac{r_s(t)}{r}}{\left(\frac{k_s}{k_p} - 1\right) \frac{r_s(t)}{r_i} + \left(\frac{k_s}{hr_c} - \frac{k_s}{k_p}\right) \frac{r_s}{r_e} + 1} \quad (2)$$

The interface conditions here have the standard form:

$$\rho_s L_F \frac{dr_s(t)}{dt} = k_s \left[\frac{\partial \theta(r, t)}{\partial r} \right]_{r=r_s(t)} = \frac{-\Phi_i}{4\pi r_s^2(t)} \quad (3)$$

The determination of Φ_i before crystallisation starts and after crystallisation is finished is done considering the uniform PCM temperature and it is possible to write that the internal energy variation in the PCM is equal to the flux that leaves the nodule.

The heat transfer coefficient between the nodule and the fluid is determined by a correlation type $Nu = f(Re, Pr)$ and so are depending on the flow rate and on the fluid temperature.

3.2.2. Modelling the discharge mode

Supercooling occurs only upon crystallisation but never upon melting. So, all the nodules from each layer simultaneously pass through the phase change at the melting temperature T_m . Equation 1 becomes :

$$\rho c_{Pf} V \frac{dT_c}{dt} = \rho c_{Pf} q_c (T_m - T_{m+1}) + N \Phi_i \quad (4)$$

According to a simplifying assumption melting-front is considered to be concentric and equations for Φ_i are the same than for crystallisation. During the melting process, heat transfer is undergoing upon natural convection and conduction. Only heat conduction equation is kept into consideration but an apparent thermal conductivity [7] is used in order to take into account the natural convection.

3.2.3. Validation of the model

The accuracy of the model has already been confirmed [4,5] by comparison between the experimental results and the results given by the numerical simulation for controlled conditions of flow rate and of inlet temperature concerning the charge mode and the discharge mode.

For actual systems, the inlet temperature of the fluid in the tank is not controlled but depends on the refrigerating capacity upon the charge mode and depends on the useful refrigerating capacity upon the discharge mode. Furthermore the flow rate can vary. The simulation of an air conditioning plant, whose results have been already presented in a previous paper [8], has also given good results.

4. DESIGN AND MODELLING THE DIFFERENT COMPONENTS OF THE PLANT.

4.1. The turbine

The selected turbine is a land turbo-alternator used for Combined Heat and Power generation. It can run with oil or natural gas; last one is retained for a higher output of the machine. The mechanical power is of 1115 kW with an ambient air temperature of 15°C and power drop is 9 kW when the temperature of the air increases 1°C. So, with 40°C, the power is only 890 kW involving, compared to the standard conditions (15°C), a fall of 225 kW that is to say 20% of the capacity. The electric output is equal (taking into account the efficiency of the alternator) to 96 % of the mechanical power.

4.2. The exchanger

The exchanger incorporates cooling coils (cooling battery). Cooling coils have copper tubes and continuous aluminium fins. Its characteristics are related to the size of the turbo-alternator. It is designed to cool, from 40°C to 15°C, 6 kg/s air (maximum mass flow rate in the turbine) with a relative humidity of 60 % by means of glycol water whose temperature varies along the exchanger from 2°C to 7°C. The value 15°C is selected for air temperature because it corresponds to the standard conditions of turbine operation. The air pressure drop caused by the device must be limited so that the turbine mechanical power should not be reduced. The selected exchanger whose pressure drop is 120 Pa only induces a mechanical power drop of 0.2 %. The air and the coolant are arranged in counterflow. The company which designs and manufactures the exchanger does not give us access to the code of simulation of the coils. On the other hand it enabled us to make use of their selection aid software. The software determines the state of the two fluids on the outlet side of the exchanger since the state and the flow rate of the two fluids at the inlet are defined. From software results a simplified model has been established which permits us to calculate the required total heat capacity of the battery. Heat fluxes are then introduced into the general modelling of the installation.

It is necessary to distinguish the wet mode with vapour condensation on the exchange surface from the dry mode [9]. The exchanged flux in dry mode is given by : $P = U S \Delta T_{mL}$ with U the overall heat transfer coefficient, S the total external surface and ΔT_{mL} the log mean temperature difference between the two fluids. The heat flow exchanged between the coolant and the wet air during the vapour condensation can be calculated by : $P = K S \Delta H_{mL}$ with K the total enthalpy exchange coefficient and ΔH_{mL} the log mean difference in enthalpy between airstream and surface defined as follows with the assumption that the saturated air temperature on the external battery wall is similar to the internal fluid temperature :

$$\Delta H_{mL} = \frac{(H_{ae} - H_{fs}) - (H_{as} - H_{fe})}{\ln \left(\frac{H_{ae} - H_{fs}}{H_{as} - H_{fe}} \right)} \quad (5)$$

From the simulation results given by the manufacturer's software, we can, thanks to the heat power calculation relations presented above, determine the value of the

coefficient K in wet mode and the value of the coefficient U in dry mode.

These coefficients only practically depend on the glycol water flow rate and the air flow rate into the exchanger. We have established a correlation giving the values of K and of U only depending on the flow rates. The effectiveness - Number of Transfer Units (NTU) method enables us to calculate the exchanged heat transfer rate by knowing only the characteristics of the fluids (air and glycol water) at the inlet of the battery.

$$P = E q_{air} c_{Pair} (T_{ae} - T_{fe}) \quad \text{dry mode}$$

$$P = E q_{air} (H_{ae} - H_{fe}) \quad \text{wet mode}$$

The effectiveness E is a function of the fluid flowing mode, of the heat capacity ratio $R = \frac{q_{air} c_{Pair}}{q_f c_{Pf}}$ and of the

NTU number with : $NTU = \frac{KS}{q_{air}}$ for the wet mode or

$$NTU = \frac{US}{q_{air} C_{p_{air}}} \quad \text{for the dry mode.}$$

Although the geometry of the exchanger is complex, the selected relation of the effectiveness, valid for a counter flow exchanger, gives very good results. The heat transfer rate value makes it possible to determine the outlet temperatures of the fluids, either directly for the coolant, or via the humid air enthalpy for the air : $P = q_f c_{Pf} (T_{fs} - T_{fe})$ or $P = q_{air} (H_{as} - H_{ae})$.

4.3. Refrigerating machine

The refrigerating machine which consumes a part of the electric output supplied by the turbine is dimensioned to charge the tank storage during the hours of electric overproduction i.e. during the night for our case. The capacity is considered to be sufficient if storage is complete, that is to say, in practice, when glycol water comes out the tank with -10°C . The available duration for the charge mode is about 8 hours. To simulate the refrigerating machine characteristics, supposed compression type, their variation according to the operating conditions are taken into account. The temperature of condensation is supposed to be constant. The temperature of evaporation decreases as the charge mode proceeds, involving a performances drop which is simulated by relations suggested by a refrigerating machines manufacturer. For a glycol water temperature of 0°C and an ambient temperature of 40°C , the realistic efficiency, i.e. the ratio of the refrigerating power to the electric power input, was estimated to 2.3.

5 CHOICE OF THE PARAMETERS AND RESULTS

5.1. Climate

Simulation is tested on one standard day, hot and wet in New Delhi in August (see Figure 2) during which the temperature varies from 26°C to 37°C and the relative humidity from 50 % to 80 %. It should be noted that only the high temperature is penalising for the turbine since it is well known that moisture does not have an influence on the capacities of a gas turbine. On the other

hand the hot and wet air will be more difficult to cool and this choice will make it possible to dimension the cooling system for the most constraining case.

5.2. Histogram of the electric load

The electric production of the turbine must meet the electric requirement of the plant. For the tested case we consider a traditional type of electric load (see Figure 3), corresponding to a diurnal activity of which the maximum (1150 kW) is provided by the turbine for an outside temperature of 11°C . On Figure 3 the required power and the selected turbine power are superimposed. So we can see that electric turbine output which varies according to the ambient temperature is insufficient during the hot hours of the day.

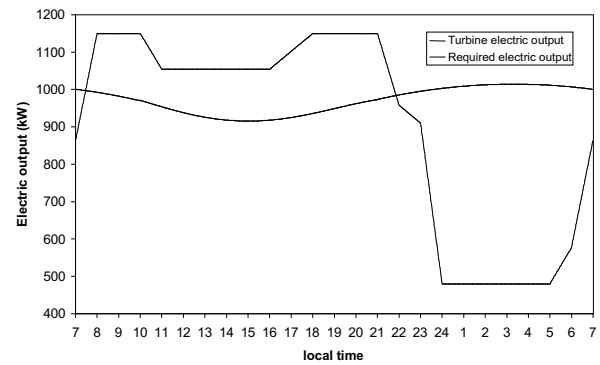


Figure 3 : Comparison between the electric output required and the electric capacity provided by the turbine without cooling.

5.3. Results

Figure 4 presents, versus time, the comparison between the required power and the turbine power. The latter depends on the air cooling and is represented on this figure for three sizes of storage tank (34.4 m^3 ; 41.7 m^3 ; 51.5 m^3). These curves must be analysed by taking into account the turbine power without inlet air cooling, indicated on Figure 3. The simulation starts on 7h00. The storage tank is supposed completely charged. The refrigerating machine is off and only storage is required for the inlet air cooling. From 7h30 the ambient conditions are such as the turbine alone cannot meet the required power. An inlet air cooling is necessary and until 17h30 the three sizes of tank make it possible to solve the problem. From this date only the tank of 51.5 m^3 volume provides a sufficient cooling in order to enable a correct operation of the plant. This volume corresponds to a cylindrical tank 2.5 m diameter and 10.5 m high.

At the end of the day, electric requirement is decreasing but it is necessary to add the refrigerating machine consumption for storage charging. This one can start up only if the available power is sufficient i.e. if the difference between the power provided by the turbine and the required power is equal to the refrigerating machine electric consumption. Around 23h30 the refrigerating unit starts. Three different curves according to the tank size are obvious again. The

highest required power naturally corresponds to the largest volume since the available duration for storage is the same one in any case. The electric output consumed by the refrigerating machine are, for each case and for a glycol water temperature of 0°C: 173 kW for 34.4 m³; 209 kW for 41.7 m³; 256 kW for 51.5 m³.

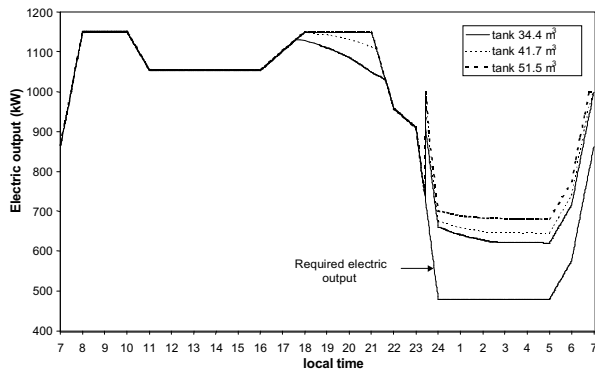


Figure 4 : Comparison between electric capacity provided by the turbine for 3 different sizes of tank and the electric load.

Figure 5 allows, thanks to the representation of the variations of some temperatures, to know the state of the storage tank all along the day. Only results concerning the tank of 51.5 m³ volume are represented. The temperatures of ambient air and of inlet air turbine are compared. At 7h30 the air is cooled from 27°C to 11°C to make it possible for the turbine to provide the required power. At 21h30 cooling is not needed any more and the two temperatures are identical.

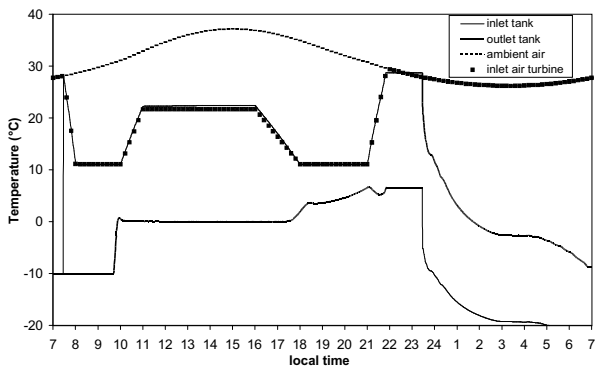


Figure 5 : Variation, versus time, of the ambient temperature, the inlet air temperature of the turbine and the water glycol temperatures at the inlet and at the outlet sides of the tank.

The change of glycol water temperatures at the inlet and at the outlet of the tank makes it possible to distinguish the charge mode from the discharge mode. As long as cooling is needed, i.e. until 22h, the inlet temperature of the tank is the same one as that which comes out of the exchanger. The selected exchanger has a good efficiency and the two outlet temperatures (air and glycol water) are practically identical. It is the discharge mode starting from a tank initially with -10°C. The

distinct plateau at 0°C for the outlet temperature is corresponding to the PCM melting point. The second significant phase of required power (from 18h to 21h) is supplied, thanks to a more significant flow in the tank, by actuating the mixing three-ways. Consequently, for the tank outlet temperature increases and tends to the inlet temperature, that is the end of the discharge mode. When cooling is not needed any more and when the refrigerating machine cannot start yet (between 22h and 23h30), there is no flow in the tank and the temperatures into the tank remain stationary.

The charge mode starts at 23h30 and the flow in the tank is reversed. The coldest temperature is now the inlet temperature for the tank. The observation of the outlet temperature highlights the supercooling phenomenon. One can notice, indeed, that the temperature plateau which corresponds to the PCM crystallisation occurs at a temperature lower than 0°C while the melting stage is strictly located at 0°C. The outlet temperature drop after the plateau indicates that it is the end of the phase change. When the temperature reaches -10°C the tank is estimated to be entirely charged.

6. CONCLUSION

The association of a refrigeration storage in order to carry out the inlet air cooling enables the designer to select a lower capacity turbine. The benefit is linked to the investment of a refrigerating machine and a storage system. Moreover, the number of hours per day that inlet air cooling is required tends to greatly influence the feasibility of thermal storage systems. Also the greater the difference of cost between on-peak and off-peak parasitic power is, the more advantageous thermal storage is. Only an economic survey adapted to each case can determine the appropriateness of the use of refrigeration storage to cool turbine inlet air.

On the other hand the modelling which makes it possible to dimension the cooling system when the climate and the electric requirement versus time are known is the first step essential to the decision-making. The modelling could also simulate operations close to that studied in this paper where cooling would be supplied by the use of refrigeration storage but also at the same time by a direct refrigerating production. In this way various strategies of control of installation could be defined.

The studied case is the most unfavourable since the climate is hot and wet. A hot and dry climate is also penalising for the turbine operation but the dry air cooling requires less power. So the size of the tank and the refrigerating machine are smaller involving a lower investment.

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NOMENCLATURE

c_{pair}	specific heat of the air
c_{pf}	specific heat of the heat transfer fluid
h	heat transfer coefficient nodule - fluid
H_{ae}	air enthalpy at the inlet of the battery
H_{as}	air enthalpy at the outlet of the battery
H_{fe}	saturated air enthalpy at the inlet of the battery at the inlet fluid temperature.
H_{fs}	saturated air enthalpy at the inlet of the battery at the outlet fluid temperature
k_s	thermal conductivity of solid PCM
k_p	thermal conductivity of the envelope of the nodule
K	heat transfer coefficient
L_F	latent heat of fusion of PCM
P	heat transfer rate of the exchanger
q_c	volumetric fluid flow quantity into the tank
q_{air}	mass flow rate of the air
q_f	mass flow rate of the fluid in the exchanger
$r_s(t)$	inner radius of the solid PCM.
r_e, r_i	external and inner radius of the nodule
S	surface of the battery
S_{nod}	surface of the nodule
T_F	PCM melting temperature
$T_c(t)$	fluid temperature into the tank
T_{ae}	inlet air temperature of the battery
T_{as}	outlet air temperature of the battery
T_{fe}	inlet fluid temperature of the battery
T_{fs}	outlet fluid temperature of the battery
T_M	melting temperature
U	overall heat transfer coefficient battery
V	volume of the fluid in a mesh
Greek symbols	
ΔT_{mL}	log mean temperature difference between the two fluids
ΔH_{mL}	log mean difference in enthalpy between the two fluids
Φ_i	Heat transfer rate exchanged by a nodule i
$\theta(r,t)$	PCM temperature in a nodule at the radius r and the time t.
ρ	fluid density
ρ_s	solid PCM density
Abbreviation	
PCM	Phase Change material